



BK3231 Bluetooth HID SoC Datasheet

Preliminary Specification

Beken Corporation
3A,1278KeyuanRd,Zhangjiang High-Tech Park
Pudong New Distrinct,Shanghai,201203, China
Tel: (86)21 51086811
Fax: (86)21 60871277

This document contains information that may be proprietary to, and/or secrets of, Beken Corporation. The contents of this document should not be disclosed outside the companies without specific written permission.

Disclaimer: Descriptions of specific implementations are for illustrative purpose only, actual hardware implementation may differ.



Table of Contents

1 General Description 3
2 Features..... 3
3 Pin Information..... 3
4 Memory Orgnization 8
5 Interrupt and Clock Unit 8
6 MFC 11
7 GPIO 12
8 ADC..... 14
9 UART 16
10 I2C-SMBus 18
11 SPI 20
12 PWM Timer..... 22
13 Watch dog 23
14 Electrical Specifications..... 24
15 Package Information 25
 15.1 QFN 7X7 56PIN:..... 25
 15.2 QFN4X4 32PIN:..... 26
16 Application Schematic 27
 16.1 QFN7X7 56PIN:..... 27
 16.2 QFN4X4 32PIN:..... 27
17 Order Information 28

1 General Description

The BK3231 chip is a highly integrated single-chip Bluetooth 3.0 HID device. It integrates the high-performance transceiver, rich features baseband processor, and Bluetooth HID profile. The FLASH program memory makes it suitable for customized application, and it is also possible for other Bluetooth application such as SPP controller.

2 Features

- Operation voltage from 2.0V to 3.6 V
- Bluetooth 3.0 compliant
- -86dBm sensitivity for 1 Mbps mode and 2 dBm transmit power
- HID v1.0, and other light profile by request
- 16 MHz crystal reference clock
- 56-pin QFN 7mmx7mm package for keyboard
- I2C, SPI and UART interface
- 10-bit Battery monitor ADC
- Three timers with PWM mode

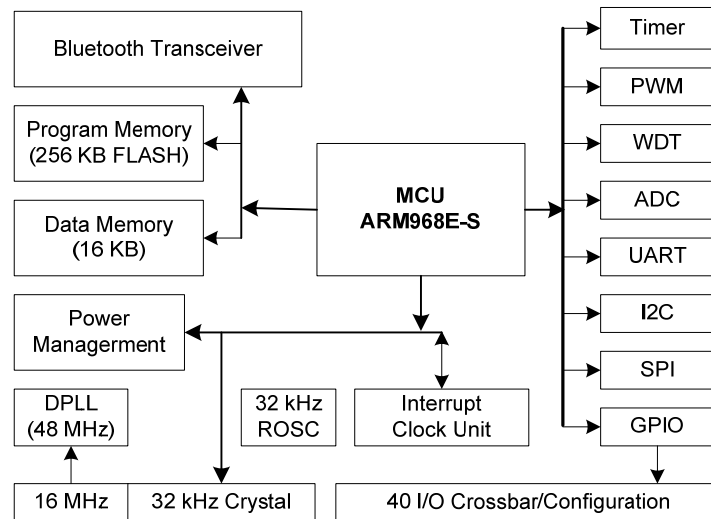


Figure 1 Block Diagram

3 Pin Information

The next diagram shows QFN56 format for the full functions usage. It can be used as keyboard TX part and total 35 GPIO available. Other package type such as QFN40 or even QFN32 is also available by request with less GPIO.

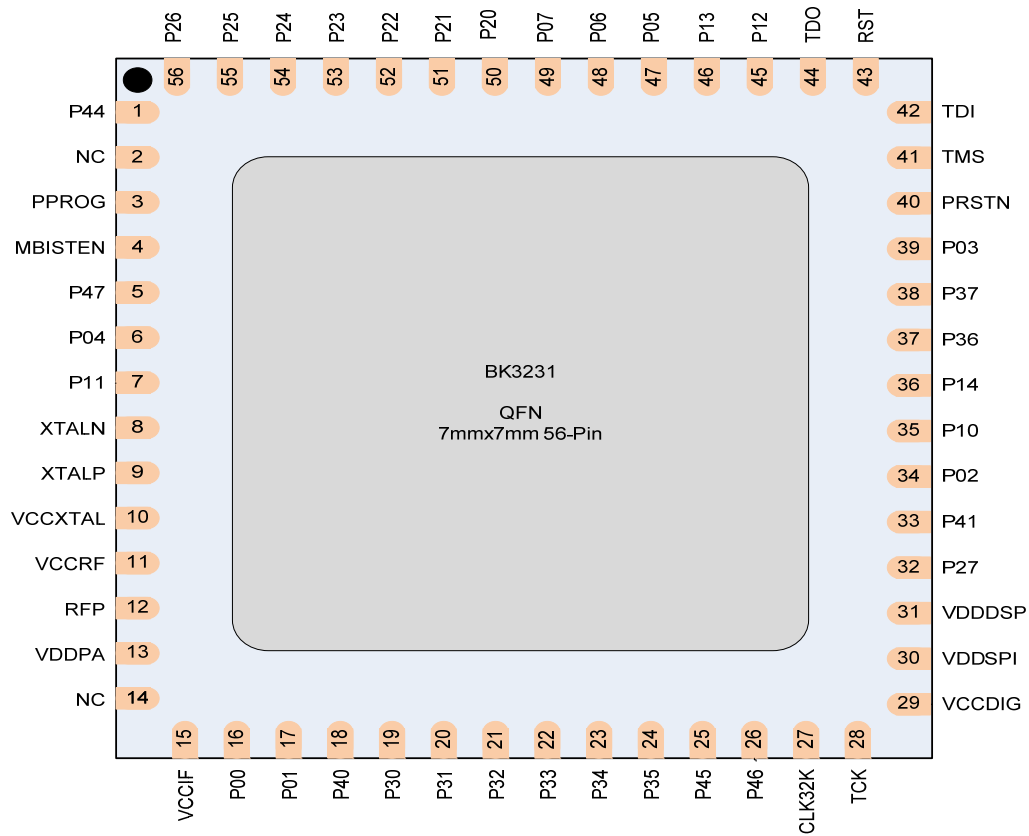


Figure 2BK3231QFN56Pin Assignment

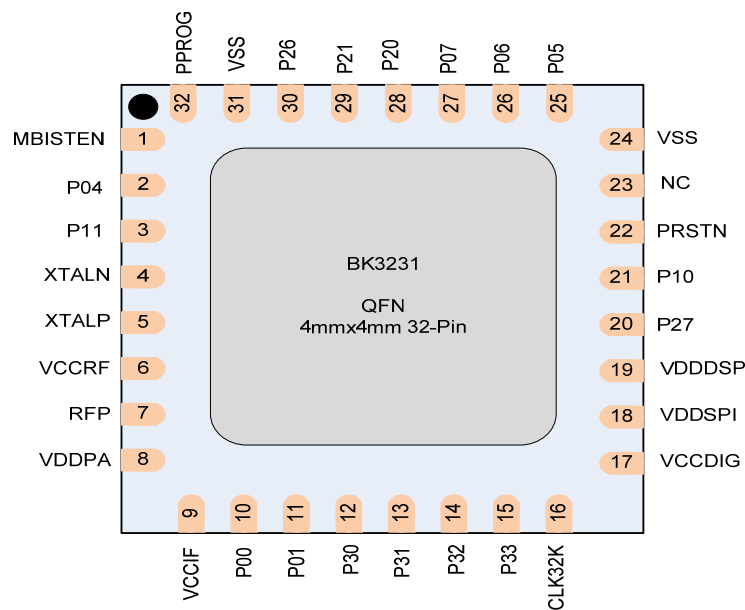


Figure 3BK3231QFN32Pin Assignment



Table 1BK3231 QFN56 Pin Description

PIN	Name	Pin Function	Description
1	P44	Digital I/O	General I/O
2	NC	NC	Not connected
3	PPROG	Digital I/O	FLASH programming selection
4	MBISTEN	Digital I/O	Test enable
5	P47	Digital I/O	General I/O
6	P04	Digital I/O	General I/O, or MOSI for SPI
7	P11	Digital I/O	General I/O, or input for external active low interrupt
8	XTALN	Analog output	Oscillator output
9	XTALP	Analog input	Oscillator input
10	VCCXTAL	Power supply	3 V supply
11	VCCRF	Power supply	3 V supply
12	RFP	RF port	RF input and output
13	VDDPA	Power output(LDO output)	1.5 V supply to PA
14	NC	NC	Not connected
15	VCCIF	Power supply	3 V supply
16	P00	Digital I/O	General I/O
17	P01	Digital I/O	General I/O
18	P40	Digital I/O	General I/O
19	P30	Digital I/O or analog input	General I/O, or input of ADC0
20	P31	Digital I/O or analog input	General I/O, or input of ADC1
21	P32	Digital I/O or analog input	General I/O, or input of ADC2
22	P33	Digital I/O or analog input	General I/O, or input of ADC3
23	P34	Digital I/O or analog input	General I/O, or input of ADC4
24	P35	Digital I/O or analog input	General I/O, or input of ADC5
25	P45	Digital I/O	General I/O
26	P46	Digital I/O	General I/O
27	CLK32K	Analog input	Clock 32 kHz input
28	TCK	Digital I/O	JTAG pin
29	VCCDIG	Power supply	3 V supply
30	VDDSPI	Analog output	Power output, connected with decoupling CAP
31	VDDDSP	Analog output	Power output, connected with decoupling CAP
32	P27	Digital I/O	General I/O, or enable for PWM1
33	P41	Digital I/O	General I/O
34	P02	Digital I/O	General I/O
35	P10	Digital I/O	General I/O, or input for external interrupt 0, active low
36	P14	Digital I/O	General I/O



37	P36	Digital I/O	General I/O, or input of ADC6
38	P37	Digital I/O	General I/O, or input of ADC7
39	P03	Digital I/O	General I/O
40	PRSTN	Digital I/O	Active low whole chip reset
41	TMS	Digital I/O	JTAG pin
42	TDI	Digital I/O	JTAG pin
43	RST	Digital I/O	JTAG reset
44	TDO	Digital I/O	JTAG pin
45	P12	Digital I/O	General I/O
46	P13	Digital I/O	General I/O
47	P05	Digital I/O	General I/O, or MISO for SPI
48	P06	Digital I/O	General I/O, or SCK for SPI
49	P07	Digital I/O	General I/O, or chip select for SPI
50	P20	Digital I/O	General I/O, or input for UART
51	P21	Digital I/O	General I/O, or output for UART
52	P22	Digital I/O	General I/O
53	P23	Digital I/O	General I/O, or clock for SMBUS (I2C)
54	P24	Digital I/O	General I/O, or data I/O for SMBUS (I2C)
55	P25	Digital I/O	General I/O
56	P26	Digital I/O	General I/O, or enable for PWM0

Table 2BK3231 QFN32 Pin Description

PIN	Name	Pin Function	Description
1	MBISTEN	Digital I/O	Test enable
2	P04	Digital I/O	General I/O, or MOSI for SPI
3	P11	Digital I/O	General I/O, or input for external active low interrupt
4	XTALN	Analog output	Oscillator output
5	XTALP	Analog input	Oscillator input
6	VCCRF	Power supply	3 V supply
7	RFP	RF port	RF input and output
8	VDDPA	Power output(LDO output)	1.5 V supply to PA
9	VCCIF	Power supply	3 V supply
10	P00	Digital I/O	General I/O
11	P01	Digital I/O	General I/O
12	P30	Digital I/O or analog input	General I/O, or input of ADC0
13	P31	Digital I/O or analog input	General I/O, or input of ADC1
14	P32	Digital I/O or analog input	General I/O, or input of ADC2
15	P33	Digital I/O or analog input	General I/O, or input of ADC3
16	CLK32K	Analog input	Clock 32 kHz input
17	VCCDIG	Power supply	3 V supply
18	VDDSPI	Analog output	Power output, connected with decoupling CAP



19	VDDDSP	Analog output	Power output, connected with decoupling CAP
20	P27	Digital I/O	General I/O, or enable for PWM1
21	P10	Digital I/O	General I/O, or input for external interrupt 0, active low
22	PRSTN	Digital I/O	Active low whole chip reset
23	NC	NC	Not connected
24	VSS		Connected to GND
25	P05	Digital I/O	General I/O, or MISO for SPI
26	P06	Digital I/O	General I/O, or SCK for SPI
27	P07	Digital I/O	General I/O, or chip select for SPI
28	P20	Digital I/O	General I/O, or input for UART
29	P21	Digital I/O	General I/O, or output for UART
30	P26	Digital I/O	General I/O, or enable for PWM0
31	VSS		Connected to GND
32	PPROG	Digital I/O	FLASH programming selection

4 Memory Orgnization

Table 1 The Memory Orgnization

	Start Address	End Address	Total (Bytes)
Program Memory			
Flash	0x00000000	0x0003FFFF	256K
Data Memory			
SRAM	0x00400000	0x00403FFF	16K
AHB Peripheral			
(MFC)	0x00800000		
APB Peripheral			
Bluetooth Transceiver	0x00900000		
ICU	0x00920000		
UART	0x00930000		
IIC	0x00940000		
SPI	0x00950000		
GPIO	0x00960000		
WDT	0x00970000		
TIME	0x00980000		
ADC	0x009a0000		

By setting PPROG-pin to 1, the internal FLASH program memory can be written with four GPIO as a SPI slave. To access the FLASH memory with internal program, please refer to MFC section for detail.

5 Interrupt and Clock Unit

There are three main clock sources: 32.768 kHz XTAL, 16 MHz XTAL and 48 MHz DPLL. The MCU clock can be selected from one of them, while the peripherals use only one constantly.

Table 2 Clock Register Mapping - 0x00920000

Register Address	Name	Description
0x0[1:0]	hfsrc	0: 32.768 kHz 1: 16 MHz XTAL clock 2: 48MHz DPLL 3: 0 MHz
0x1[7:1]	core_clk_divid	MCU clock divided ratio: 0~127
0x1[8]	core_clk_pwd	1: Power down MCU clock 0: Active MCU clock
0x3[8:0]	UART clk's Setting	Same definition as MCU clock setting by REG1[8:0] The UART main clock is 16 MHz
0x4[8:0]	I2C clk's Setting	Same definition as MCU clock setting by REG1[8:0] The I2C main clock is 16 MHz
0x5[8:0]	PWM clk's Setting	Same definition as MCU clock setting by REG1[8:0] The PWM main clock is 32.768 kHz
0x6[8:0]	WDT clk's Setting	Same definition as MCU clock setting by REG1[8:0] The PWM main clock is 32.768 kHz
0x8[8:0]	SPI clk's Setting	Same definition as MCU clock setting by REG1[8:0] The SPI main clock is 16 MHz
0x9[8:0]	ADC clk's Setting	Same definition as MCU clock setting by REG1[8:0] The ADC main clock is 16 MHz

The ARM968E-S supports two interrupt level. The FIRQ has higher priority than nIRQ. In the BK3231, all peripheral interrupts are nIRQ except the Bluetoothtransceiver. All interrupt can be enabled, disabled, and cleared. There is two low power modes: MCU stop and deep sleep, and any interrupt can be configured to be a wake up source to let MCU exit low power mode.

Table 3 Interrupt Register Mapping - 0x00920000

Register Address	Name	Description
0xa[9:0]	int_enable[9:0]	Interrupt enable control bit [1]
0xa[10]	irq_enable	Enable ARM nIRQ
0xa[11]	fiq_enable	Enable ARM FIRQ
0xa[14:12]	ext_int0_cfg[2:0]	External interrupt 0 configuration bit[2]: Enable contro bit bit[1:0] 3, posedge trigger

		2, negedge trigger 1, high level trigger 0, low level trigger
0xa[17:15]	ext_int1_cfg[3:0]	External interrupt 1 configuration bit[2]: Enable contro bit bit[1:0] 3, posedge trigger 2, negedge trigger 1, high level trigger 0, low level trigger
0xa[27:18]	int_wakena[9:0]	Wakeup enable control bit [1]
0xb[9:0]	int_clear[9:0]	Interrupt clear control bit [1]
0xc[9:0]	int_status[9:0]	Interrupt status control bit [1]
0x10[31:0]	gpio_deep_waken[31:0]	Enable GPIO[31:0] as wake up source from deep sleep mode
0x11[7:0]	gpio_deep_waken[39:32]	Enable GPIO[39:32] as wake up source from deep sleep mode
0x11[31:16]	gpio_deep_sleep	Write16'h3231 to enable the IC enter deep sleep mode
0x13[0]	gpio_int_enable	Enable the GPIO interrupt [2]
0x13[1]	gpio_int_wakena	Enable GPIO be wake up source from MCU stop mode
0x13[2]	gpio_int_clear	Clear the GPIO interrupt
0x13[3]	gpio_int_status	GPIO interrupt status

Note 1:

The 10 interrupt source is defined as follows.

bit[0]	External Interrupt 0
bit[1]	External Interrupt 1
bit[2]	PWM timer 0
bit[3]	PWM timer 1
bit[4]	PWM timer 2
bit[5]	I2C Interrupt
bit[6]	UART Interrupt
bit[7]	Bluetooth transceiver interrupt
bit[8]	SPIInterrupt
bit[9]	ADCInterrupt

Note 2:

This single bit is combined logic of 40 GPIOs. To clear the single bit status, user should firstly clear the individual bit of the status of each GPIO interrupt in GPIO module

6 MFC

To avoid unintentional FLASH operation, serial strict steps must be executed before write or erase the FLASH. For example, if you want to write the FLASH, the next steps should be executed.

1. Set the right register to point to the space you want to operate firstly
2. Then write the configuration data and address
3. Write the right byte to Remove the protect condition
4. Write the right key number sequentially
5. Set the control bit to start the operation
6. Wait until the start bit change to zero
7. Set the control bit to protect the flash space for avoiding wrong operation

The read and erase process is similar to the write process

In the period of FLASH operation, The ARM will enter into IDLE state until the current operation finished.

You should erase the corresponding FLASH address firstly before program any data into it.

Table 4 Interrupt Register Mapping - 0x00800000

Addresses	Name	Description
0x00[15:0]	KEYWORD	Write "0x58A9" and then "0xA958" to enable FLASH operation; After once operation finished, it will be disabled automatically
0x01[0]	START	write 1 to start operate flash; it will be cleared by hardware after the operation finished
0x01[1]	ERROR	Error happened when =1; write 0 to clear it. Don't write 1 to this bit.
0x01[4:2]	CONTROL	000: read 001: write 010: sector erase; 011: block erease 111: chip erase others : error happen; START will be cleared now
0x01[6:5]	SPACE control	00:main space 01:NVR space 10:RDN space 11:main space
0x02[15:0]	ADDR	Opearation address

0x03[31:0]	DATA	Data write into flash or the data read from flash
0x04[7:0]	DATA	FLASH W/E protect register 0(must =0xa5)
0x05[7:0]	DATA	FLASH W/E protect register 2(must =0xc3)
0x06	DATA	FLASH W/E protect register 3; Write any data into this address will disable W/E, and can't enable except RESET happened. Default enable after power on.
0x07	DATA	FLASH W/E protect register 4; Write any data into this address will disable ARM directly write function, and can't enable except RESET happened. Default enable after power on.

7 GPIO

There are eight groups total forty general purpose input and output ports. All the four port can be used for general I/O with selectable direction for each bit, or these lines can be used for specialized functions.

When the port is configured as general I/O, the detail function of them can be set by register as follows.

Table 5 GPIO0 Register Mapping - 0x00960000

0x0[0]	GPIO_Input	GPIO0 Input Bits
0x0[1]	GPIO_Output	GPIO0 Output Bits
0x0[2]	GPIO_Input_Ena	Input Enable, High Active
0x0[3]	GPIO_Output_Ena	Output Enable, Low Active
0x0[4]	GPIO_Pull_Mode	1: PullUp, 0: PullDown
0x0[5]	GPIO_Pull_Ena	GPIO0 Pull Up/Down Enable
0x0[6]	GPIO_Fun_Ena	GPIO0 2nd Function Enable
0x0[7]	Input_Monitor	View GPIO0's Inputs Value

GPIO1 to GPIO39 has the same definition but with address from 0x1 to 0x27.

Any GPIO can be interrupt source, and each GPIO has its own control bit as follows.

Table 6 GPIO Interrupt Control Register Mapping - 0x00960000

0x30	INT_EN[31:0]	GPIO[31:0] interrupt enable control bit (1)
0x31	INT_EN[39:32]	GPIO[39:32] interrupt enable control bit (1)
0x32	INT_LEV[31:0]	GPIO[31:0] interrupt trigger level 1: High; 0: Low



0x33	INT_LEV[39:32]	GPIO[39:32] interrupt trigger level 1: High; 0: Low
0x34	INT_STA[31:0]	GPIO[31:0] interrupt status
0x35	INT_STA[39:32]	GPIO[39:32] interrupt status

Most GPIO have special function mapping, and the GPIO will be used as the special functional pin when the contro bit (bit 6 GPIO_Fun_Ena) is enabled.

Table 7 GPIO Functinal Mapping

GPIO Pin Name	PPMODE=1	2 nd function Mode	GPIO Mode	GPIO bit number
GPIO00	spi_prog_clk	bb_tx_bit Out	General I/O	GPIO00
GPIO01	spi_miso	bb_rx_bit Out	General I/O	GPIO01
GPIO02			General I/O	GPIO02
GPIO03			General I/O	GPIO03
GPIO04		SPI MOSI	General I/O	GPIO04
GPIO05		SPI MISO	General I/O	GPIO05
GPIO06		SPI SCK	General I/O	GPIO06
GPIO07		SPI CS	General I/O	GPIO07
GPIO08	spi_mosi	External Interrupt 0	General I/O	GPIO10
GPIO09	spi_cs	External Interrupt 1	General I/O	GPIO11
GPIO10			General I/O	GPIO12
GPIO11			General I/O	GPIO13
GPIO12			General I/O	GPIO14
GPIO13			General I/O	GPIO15
GPIO14		UART CTS(Out)	General I/O	GPIO16
GPIO15		UART RTS(In)	General I/O	GPIO17
GPIO16		UART_RX	General I/O	GPIO20
GPIO17		UART_TX	General I/O	GPIO21
GPIO18			General I/O	GPIO22
GPIO19		I2C SCLK	General I/O	GPIO23
GPIO20		I2C SDA	General I/O	GPIO24
GPIO21			General I/O	GPIO25
GPIO22		PWM0 Output	General I/O	GPIO26
GPIO23		PWM1 Output	General I/O	GPIO27
GPIO24		ADC0	General I/O	GPIO30
GPIO25		ADC1	General I/O	GPIO31
GPIO26		ADC2	General I/O	GPIO32
GPIO27		ADC3	General I/O	GPIO33
GPIO28		ADC4	General I/O	GPIO34

GPIO29		ADC5	General I/O	GPIO35
GPIO30		ADC6	General I/O	GPIO36
GPIO31		ADC7	General I/O	GPIO37
GPIO32			General I/O	GPIO40
GPIO33			General I/O	GPIO41
GPIO34			General I/O	GPIO42
GPIO35			General I/O	GPIO43
GPIO36			General I/O	GPIO44
GPIO37			General I/O	GPIO45
GPIO38			General I/O	GPIO46
GPIO39			General I/O	GPIO47

8 ADC

A 10bits SAR ADC is integrated in the BK3231. Total 8 channels can be selected used for ADC transfer. The ADC supports continue mode and single transfer mode, and the sample rate can be 1kHz to 32kHz. In single transfer mode, it will generate interrupt every time after transform.

The ADC havefour work mode, they are sleep mode, single mode, software mode and continue mode.

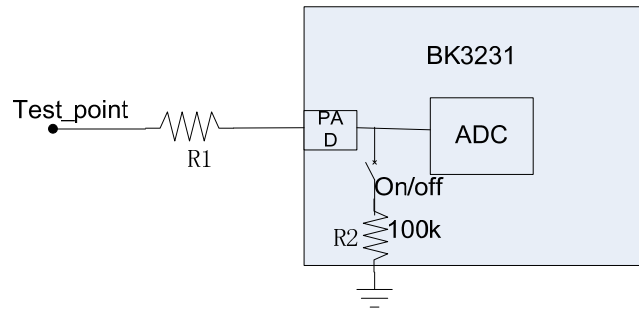
- Sleep mode(mode==00): ADC is power down now
- Single mode(mode==01): The system will enter sleep mode when transfer is done and waiting MCU to read the result. You should write mode=1 again for another transfer.
- Controlled by software(mode==10): In this mode,interrupt will be triggered after transfer and wait MCU to read. The interrupt will be cleared after MCU read, and then the transfer will start again.
- Continue mode(mode==11):The ADC will work at the sample rate set by register.

The sample rate can be calculated by the next formula:

- ◆ $F_{\text{sample}} = \text{input ADC clock} / (2^{(\text{ADC_CLK_RATE}+2)} / 36(\text{or } 18))$
- ◆ The highest sample rate is 32k

The local interrupt flag of ADC need not be cleared by software;it will be set after tranform and be cleared after the result has been read out. But the ADC INTstored ICU should be cleared after the ADC INT service finished.

Therange of input voltage is from 0v to 1.5V. If the input voltage more than 1.5V, a resistor can be added to decrease the input voltage like the next diagram.



Note: There are eight GPIO can be ADC input. When used as this:
 Voltage=data[9:0]/448; The saturate voltage is 1.5 volt.

Table 8 ADC Register Mapping – 0x009A0000

Address	Name	Description
0x0[1:0]	ADC_MODE	ADC operation mode 00: Sleep mode 01: Single mode 10: Software mode 11: Continuous mode
0x0[2]	ADC_EN	Enable ADC
0x0[5:3]	ADC_CHNL	Channel selection
0x0[6]	FIFO_EMPTY	ADC FIFO empty flag The ADC conversion result is stored at a FIFO with 4 depths
0x0[7]	ADC_BUSY	ADC busy flag
0x0[9:8]	ADC_SAMPLE_RATE	Sample rate setting 2'b00: adc_clk/36 2'b01: adc_clk/18 2'b10: reserved 2'b11: Reserved
0x0[10]	ADC_CLK_WAIT	For ADC mode 1 and mode 2, it will wait 4 (0) or 8(1) ADC_CLK cycle to start conversion after active ADC clock
0x0[18:16]	ADC_CLK_RATE	ADC clock divided ratio 000: 4 001: 8 010: 16 011: 32 100: 64 101: 128 110: 256 111: 512
0x1[9:0]	ADC_DATA	ADC conversion result

NOTE: For detecting the voltage higher than 1.5V, an additional resistor need be added to attenuate the voltage.

There is a 100k resistor R2 in the chip, you can use it to attenuate the voltage with an outer resistor R1. The usage method is described below.

REG part		description	note
XVR register 0x0910000	Reg07[13]	enable or disable the attenuation resistor in the SAR ADC 1: enable 0:disable	100k
XVR register	Reg07[12:10]	the channel number where the resistor is enabled	0~7

Table 9 ADC attenuation Register

9 UART

The UART interface has 128 bytes FIFO for both TX and RX. It will generate interrupt request when there is risk or event of FIFO underflow or overflow. For the RX, it will generate interrupt if found parity bit check error or stop bit check error.

When the UART RX line goes from idle state ('HIGH') to active state ('LOW') for a set UART clock cycle, it will generate wake up interrupt to activate MCU clock.

Table 10 UART Register Mapping – 0x00930000

0x0[0]	UART_TX_ENABLE	UART TX enable (1) or disable (0)
0x0[1]	UART_RX_ENABLE	UART RX enable (1) or disable (0)
0x0[2]	UART_IRDA	0 : UART frame structure 1 : IRDA frame structure
0x0[4:3]	UART_LEN[1:0]	UART data bit width 00 : 5 bit 01 : 6 bit 10 : 7 bit 11 : 8 bit
0x0[5]	UART_PAR_EN	Has(1) or not(0)the parity check bit
0x0[6]	UART_PAR_MODE	Odd(0) or even(1) parity check
0x0[7]	UART_STOP_LEN	STOP bit length 0 : 1 bit 1 : 2 bits



0x0[20:8]	UART_CLK_DIV[12:0]	UART band rate setting Baud rate=UART_CLK/(UART_CLK_DIV+1) UART_CLK_DIV should be greater than 4
0x0[21]	UART_TX_FIFO_EN	Clear TX FIFO (1)
0x0[22]	UART_RX_FIFO_EN	Clear RX FIFO (1)
0x1[7:0]	TX_FIFO_THRESHOLD [7:0]	When the bytes in TX FIFO is less than this threshold, it will give need write interrupt
0x1[15:8]	RX_FIFO_THRESHOLD [7:0]	When the bytes in RX FIFO is greater than this threshold, it will give need read interrupt
0x2[7:0]	TX_FIFO_COUNT[FIFO_WD-1:0]	Number of bytes in the TX FIFO
0x2[15:8]	RX_FIFO_COUNT[FIFO_WD-1:0]	Number of bytes in the RX FIFO
0x3[7:0]	UART_DOUT	UART TX data
0x3[15:8]	UART_DIN	UART RX data
0x4[0]	UART_TX_FIFO_NEED_WRITE_MASK	Enable TX FIFO need write interrupt
0x4[1]	UART_RX_FIFO_NEED_READ_MASK	Enable RX FIFO need read interrupt
0x4[2]	UART_RX_OV_MASK	Enable RX overflow interrupt
0x4[3]	UART_RX_PAR_ERR_MASK	Enable RX parity check error interrupt
0x4[4]	UART_RX_STOP_ERR_MASK	Enable RX stop bit check error interrupt
0x4[5]	TX_STOP_END_MASK	Enable TX finished interrupt
0x4[6]	UART_RXD_WAKE_PULSE_MASK	Enable RX wake up pulse detected interrupt
0x5[0]	UART_TX_FIFO_NEED_WRITE_WAKEUP	TX FIFO need write interrupt; Will be cleared after interrupt condition disappeared
0x5[1]	UART_RX_FIFO_NEED_READ_WAKEUP	RX FIFO need read interrupt; Will be cleared after interrupt condition disappeared
0x5[2]	UART_RX_OV	RX overflow bit error interrupt status Write 1 to clear
0x5[3]	UART_RX_PAR_ERR	RX parity bit error interrupt status Write 1 to clear

0x5[4]	UART_RX_STOP_ERR	RX stop bit error interrupt status Write 1 to clear
0x5[5]	TX_STOP_END_INT	UART TX finished interrupt status Write 1 to clear
0x5[6]	UART_RXD_WAKE_PULSE	UART wake up pulse interrupt status Write 1 to clear
0x6[6:0]	FLOW_CTL_LOW_CNT[6:0]	UART CTS and RTS flow control rx_fifo low counter threshold: when rx_fifo_counter < flow_ctl_low_cnt: CTS is set; meaning that UART is ready to receive.
0x6[14:8]	FLOW_CTL_HIGH_CNT[6:0]	UART CTS and RTS flow control rx_fifo high counter threshold: when rx_fifo_counter > flow_ctl_high_cnt: CTS is clear; meaning that UART is not ready to receive.
0x6[16]	FLOW_CTL_EN	UART CTS and RTS flow control enable
0x7[9:0]	UART_RXD_WAKE_CNT	UART RX waken up pad time threshold and low pulse RX threshold
0x7[19:10]	UART_TXD_WAIT_CNT	UART TX waiting time after sending wake up signal
0x7[20]	UART_RXD_WAKE_EN	UART RX waken up pad enable (1)
0x7[21]	UART_TXD_WAKE_EN	UART low pulse tx enable (1)

10 I2C-SMBus

The I2C I/O interface is a two-wire, bi-directional serial bus. The I2C is compliant with the System Management Bus Specification, version 1.1, and compatible with the I²C serial bus. Reads and writes to the interface by the system controller are byte oriented with the I2C interface autonomously controlling the serial transfer of the data.

Data can be transferred at up to 1/10th of the system clock as a master or slave (this can be faster than allowed by the I2C specification, depending on the system clock used). A method of extending the clock-low duration is available to accommodate devices with different speed capabilities on the same bus.

The I2C interface may operate as a master and/or slave, and may function on a bus with multiple masters. The I2C provides control of SDA (serial data), SCL (serial clock) generation and synchronization, arbitration logic, and START/STOP control and generation.

It is assumed the reader is familiar with the I2C-Bus Specification -- Version 2.0 and system Management Bus Specification -- Version 1.1.

The bi-directional SCL (serial clock) and SDA (serial data) lines must be connected to a positive power supply voltage through a pull-up resistor or similar circuit. Every device connected to the bus must have an open-drain or open-collector output for both the SCL and SDA lines, so that both are pulled high (recessive state) when the bus is free.

Table 11 I2C Register Mapping – 0x00940000

0x0[31]	ENSMB	SMBus Enable
0x0[30]	INH	SMBUS slave mode enable (0)
0x0[29]	SMBFTE	Enable bus idle detection (1) Should be enabled for master mode
0x0[28]	SMBTOE	SCL low time out detection enable (1)
0x0[27:26]	SMBCS	SMBus clock source selection 00: Timer 0 overflow 01: Timer 1 overflow 10: Timer 2 overflow 11: Internal clock (Divided ratio=FREQ_DIV)
0x0[25:16]	SLV_ADDR	SMBUS slave address
0x0[15:6]	FREQ_DIV	SMBUS main clock divided ratio
0x0[5:3]	SCL_CR	SCL active low time out threshold, is power(2, SCL_CR)
0x0[2:0]	IDLE_CR	SMBUS idle detection threshold, is power(2, IDLE_CR)
0x1[31:16]	Reserved	
0x1[15]	BUSY	SMBus busy (1)
0x1[14]	MASTER	MASTER mode (1) or slave mode (0)
0x1[13]	TXMODE	SMBus TX status (1) or RX status (0)
0x1[12]	ACKRQ	SMBus ACK (1) or not (0) at receive mode
0x1[11]	ADDR_MATCH	Address match ok (1) or not (0)
0x1[10]	STA	SMBus start condition enable (1)
0x1[9]	STO	Write: SMBus stop condition send enable (1) Read: SMBus stop condition detected (1)
0x1[8]	ACK	Write: SMBus ACK send enable (1) Read: SMBus ACK received (1)

0x1[7:6]	INT_MODE	Interrupt mode For Sender: 00,01,10,11: Data in TX FIFO is less than 1/4/8/12 byte For Receiver: 00,01,10,11: Data in RX FIFO is greater than 12/8/4/1
0x1[5]	TXFIFO_FULL	TX FIFO Full flag
0x1[4]	RXFIFO_EMPTY	RX FIFO empty flag
0x1[3]	ARBLOST	Multi-master competition failed (1)
0x1[2]	Reserved	
0x1[1]	SCL_TMOT	SCL low time out detected (1)
0x1[0]	SI	SMBusinterrupt flag
0x2[31:8]	Reserved	
0x2[7:0]	SMB_DAT	SMBUS TX data (Write) or RX data (Read)

11 SPI

The Enhanced Serial Peripheral Interface (SPI) provides access to a flexible, full-duplex synchronous serial bus. SPI can operate as a master or slave device in both 3-wire or 4-wire modes, and supports multiple masters and slaves on a single SPI bus. The slave-select (NSS) signal can be configured as an input to select SPI in slave mode, or to disable Master Mode operation in a multi-master environment, avoiding contention on the SPI bus when more than one master attempts simultaneous data transfers. NSS can also be configured as a chip-select output in master mode, or disabled for 3-wire operation. Additional general purpose port I/O pins can be used to select multiple slave.

There are four pins for SPI interface. The master-out, slave-in (MOSI) signal is an output from a master device and an input to slave devices. It is used to serially transfer data from the master to the slave. This signal is an output when SPI is operating as a master and an input when SPI is operating as a slave. Data is transferred most-significant bit first. When configured as a master, MOSI is driven by the MSB of the shift register in both 3- and 4-wire mode.

The master-in, slave-out (MISO) signal is an output from a slave device and an input to the master device. It is used to serially transfer data from the slave to the master. This signal is an input when SPI is operating as a master and an output when SPI is operating as a slave. Data is transferred most-significant bit first. The MISO pin is placed in a high-impedance state when the SPI module is disabled and when the SPI operates in 4-wire mode as a slave that is not selected. When acting as a slave in 3-wire mode, MISO is always driven by the MSB of the shift register.

In slave mode, the data on MOSI are sampled at the middle of period of every bit. In master mode, the data on MISO are sampled at the last clock period to acquire the maximal setup time.

Table 12 SPI Register Mapping – 0x00950000

Address	Name	Description
0x0[23]	SPIEN	Enable SPI (1)
0x0[22]	MSTEN	Master mode (1) or slave mode(0)
0x0[21]	CKPHA	SPI clock phase 0: Sample data at first edge of SCK 1: Sample data at second edge of SCK
0x0[20]	CKPOL	SPI clock polarity SCK is high (1) or low (0) at idle stat 0
0x0[18]	BIT_WDTH	Bit width 0: 8bit 1: 16bit
0x0[17:16]	NSSMD	Slave mode 00: 3-wires mode 01: 4-wires mode 1x: 4-wires mode single master
0x0[15:8]	SPI_CKR	SPI clock divided ratio
0x0[7]	RXINT_EN	RX interrupt enable
0x0[6]	TXINT_EN	TX interrupt enable
0x0[5]	RXOVR_EN	RX overflow interrupt enable
0x0[4]	TXOVR_EN	TX overflow interrupt enable
0x0[3]	RXFIFO_CLR	Clear RX FIFO
0x0[2]	TXFIFO_CLR	Clear TX FIFO
0x0[1]	RXINT_MODE	RX interrupt setting when number of data in the RX FIFO is greater than 0 (0) or 8 (1)
0x0[0]	TXINT_MODE	TX interrupt setting when number of data in the TX FIFO is 0 (0) or less than 8 (1)
0x1[15]	SPIBUSY	SPI busy flag
0x1[14]	SLVSEL	Slave seleted flag when NSS is 0
0x1[12]	RXOVR	RX overflow flag
0x1[11]	TXOVR	TX overflow flag
0x1[10]	MODF	Master collision detected flag
0x1[9]	RXINT	RX interrupt flag
0x1[8]	TXINT	TX interrupt flag
0x1[3]	RXFIFO_FULL	RX FIFO full flag
0x1[2]	RXFIFO_EMPTY	RX FIFO empty flag
0x1[1]	TXFIFO_FULL	TX FIFO full flag

0x1[0]	TXFIFO_EMPTY	TX FIFO empty flag
0x2[15:0]	SPI_DAT	SPI data entry Write to TX FIFO or read from RX FIFO

12 PWM Timer

There are three timers, two of which is 16 bit and can be works as PWM waveform generator, while the other one is 20bit timer. The PWM waveform can be output to GPIO to drive external device such as LED.

Table 13 PWM Timer Register Mapping – 0x00980000

Address	Nome	Description
0x0[15:0]	PT0_CntMid[15:0]	PWM 0 Active high duration
0x0[31:16]	PT0_CounTo[15:0]	PWM 0 or counter period
0x1[15:0]	PT1_CntMid[15:0]	PWM 1 Active high duration
0x1[31:16]	PT1_CounTo[15:0]	PWM 1 or counter period
0x2[0]	PT0_Mode	0: Timer mode 1: PWM Mode
0x2[1]	PT1_Mode	0: Timer mode 1: PWM Mode
0x2[3:2]		Reserved
0x2[4]	PT0_Enable	PWM timer 0 enable (1)
0x2[5]	PT1_Enable	PWM timer 1 enable(1)
0x2[7:6]		Reserved
0x2[11:8]	PT_Divid[3:0]	PWM timer pre-divide ratio
0x2[12]	PT0_Int_flag	PWM timer 0 interrupt flag, write 1 to clear
0x2[13]	PT1_Int_flag	PWM timer 1 interrupt flag, write 1 to clear
0x3[19:0]	PT2_Counto[19:0]	Timer 2 period
0x3[20]	PT2_Enable	Timer 2 enable (1)
0x3[21]	PT2_Int_flag	Timer 2 interrupt flag, write 1 to clear

13 Watch dog

The watch dog is used to reset the whole chip when the firmware runs out of order.

Table 14 Watch Dog Register Mapping – 0x00970000

Address	Name	Description
0x0[23:16]	WDKEY[7:0]	Watch dog key To clear watch dog counter, please write 0x5A, and then write 0xA5
0x0[15:0]	WD_PERIOD[15:0]	Watch dog timer period 1: ~0.6 ms Maximum: ~38.8 second

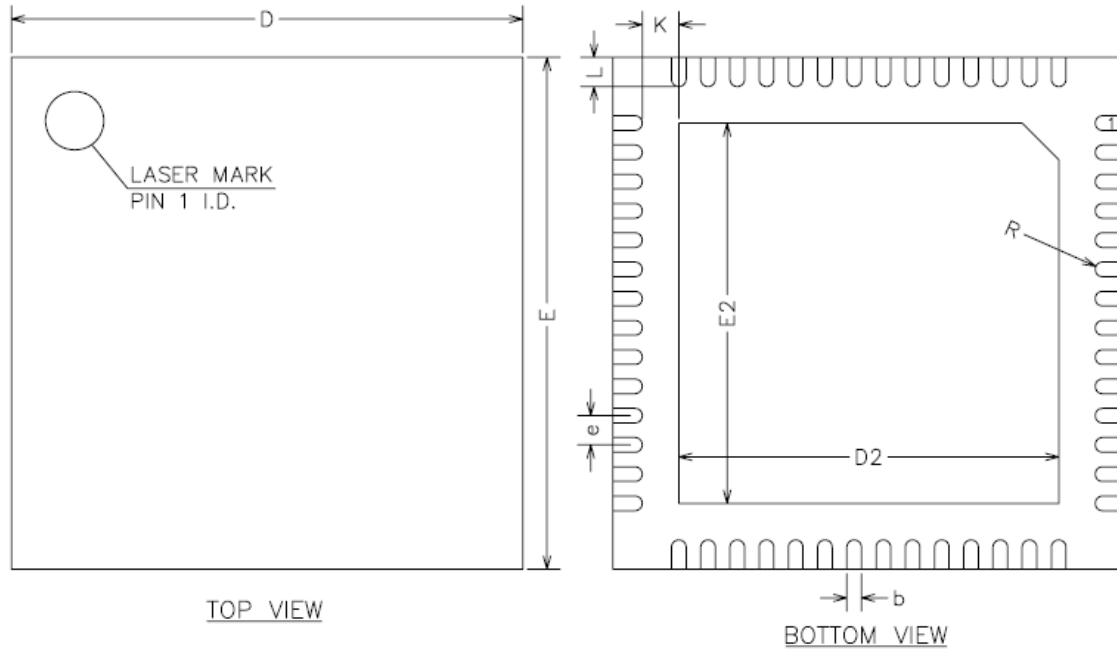
14 Electrical Specifications

Table 2RF Characteristics

Name	Parameter (Condition)	Min	Typical	Max	Unit	Comment
Operating Condition						
VCC	Voltage	2.0	3.0	3.6	V	
TEMP	Temperature	-20	+27	+80	°C	
Digital input Pin						
VIH	High level	VCC-0.3		VCC+0.3	V	
VIL	Low level	VSS		VSS+0.3	V	
Digital output Pin						
VOH	High level (IOH=-0.25mA)	VCC- 0.3		VCC	V	
VOL	Low level(IOL=0.25mA)	VSS		VSS+0.3	V	
Normal condition						
IVDD	Deep sleep		2		uA	
IVDD	Sleep mode 1 (MCU stopped)		10		uA	
IVDD	Sleep mode 2 (MCU 32 kHz)		100		uA	
IVDD	Active RX		30		mA	
IVDD	Active TX @ 2 dBm output power		22		mA	
Normal RF condition						
FOP	Operating frequency	2400		2480	MHz	
FXTAL	Crystal frequency		16		MHz	
RFSK	Air data rate		1		Mbps	
Transmitter						
PRF	Output power	-40	0	5	dBm	
PBW	Modulation 20 dB bandwidth		1		MHz	
PRF1	Out of band emission 2 MHz	-20			dBc	
PRF2	Out of band emission 3 MHz	-40			dBc	
IVDD	Current at -40dBm output power		NA		mA	
IVDD	Current at -30dBm output power		NA		mA	
IVDD	Current at -25dBm output power		NA		mA	
IVDD	Current at -10dBm output power		NA		mA	
IVDD	Current at -5dBm output power		NA		mA	
IVDD	Current at 0dBm output power		NA		mA	
IVDD	Current at 2dBm output power		22		mA	
Receiver						
Max Input	1 E-3 BER	0			dBm	
RXSSENS	1 E-3 BER sensitivity		-86		dBm	
IIP3	IIP3, Pin=-63 dBm; Punwant=-39 dBm; f0=2f1-f2, f2-f1=3 MHz or 4 MHz or 5 MHz		-18		dBm	
C/ICO	Co-channel C/I			11	dB	
C/I1ST	ACS C/I 1MHz			0	dB	
C/I2ND	ACS C/I 2MHz			-30	dB	
C/I3RD	ACS C/I 3MHz			-40	dB	
C/I1STI	ACS C/I Image channel			-9	dB	
C/I2NDI	ACS C/I 1 MHz adjacent to image channel			-20	dB	

15 Package Information

15.1 QFN 7X7 56PIN:

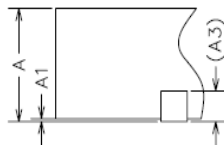


COMMON DIMENSIONS
(UNITS OF MEASURE=MILLIMETER)

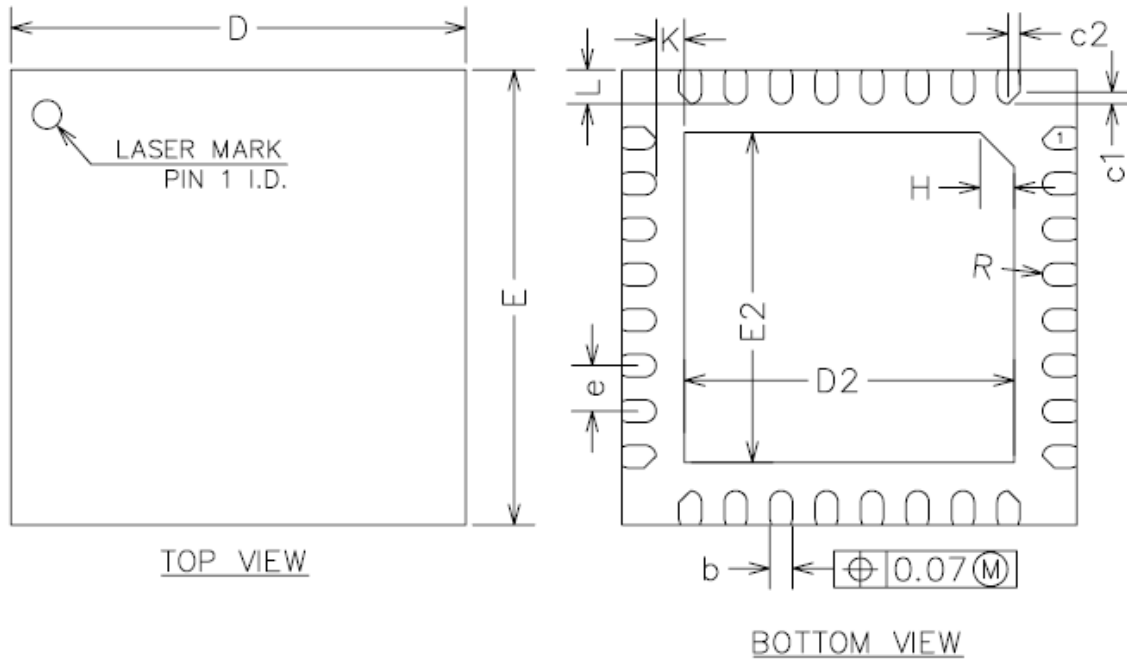
SYMBOL	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	0	0.02	0.05
A3	0.20REF		
b	0.15	0.20	0.25
D	6.90	7.00	7.10
E	6.90	7.00	7.10
D2	5.05	5.20	5.35
E2	5.05	5.20	5.35
e	0.30	0.40	0.50
K	0.20	-	-
L	0.35	0.40	0.45
R	0.09	-	-



SIDE VIEW

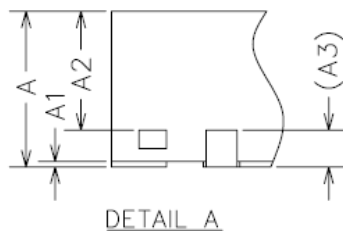
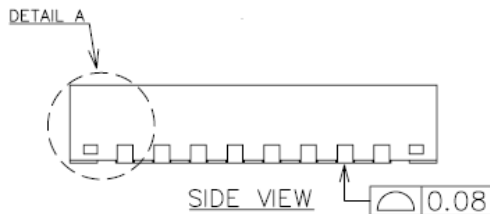


15.2 QFN4X4 32PIN:



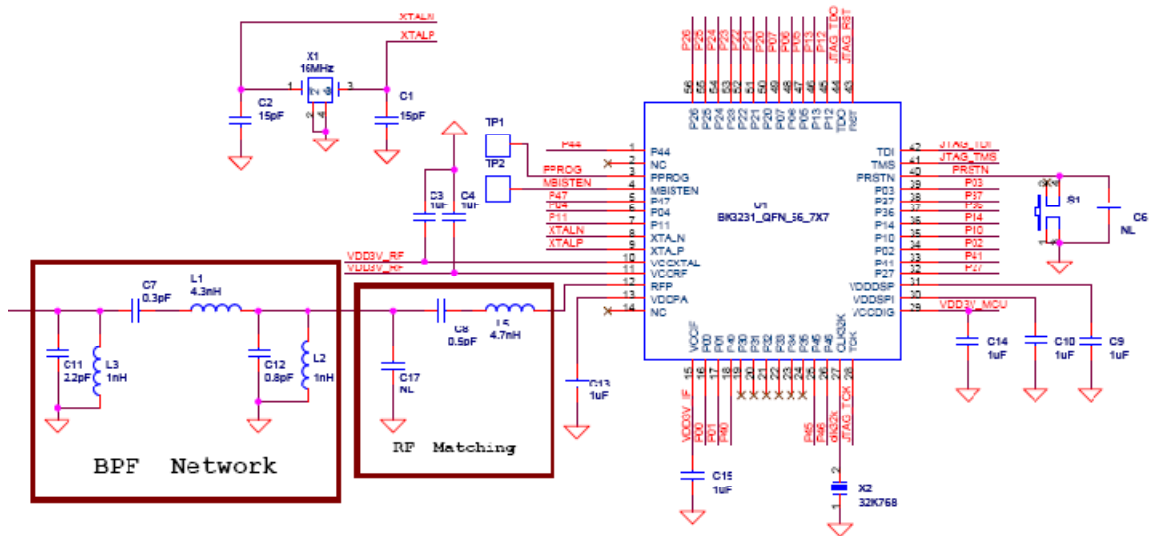
COMMON DIMENSIONS
(UNITS OF MEASURE=MILLIMETER)

SYMBOL	MIN	NOM	MAX
A	0.80	0.85	0.90
A1	0	0.02	0.05
A2	0.60	0.65	0.70
A3	0.20REF		
b	0.15	0.20	0.25
D	3.90	4.00	4.10
E	3.90	4.00	4.10
D2	2.80	2.90	3.00
E2	2.80	2.90	3.00
e	0.30	0.40	0.50
H	0.30REF		
K	0.25REF		
L	0.25	0.30	0.35
R	0.09	-	-
c1	-	0.10	-
c2	-	0.10	-

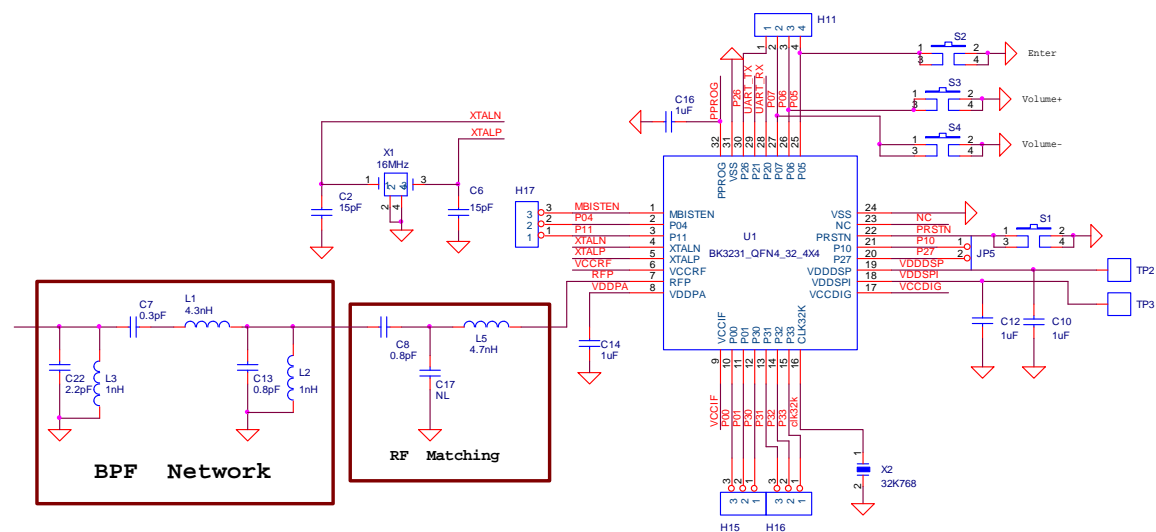


16 Application Schematic

16.1 QFN7X7 56PIN:



16.2 QFN4X4 32PIN:





17 Order Information

Part number	Package	Packing	Minimum Order Quantity
BK3231QB	QFN7x7-56Pin	Tape Reel	3000
BK3231Q32	QFN 4mmx4mm 32-Pin	Tape Reel	10K

射频和天线设计培训课程推荐

易迪拓培训(www.edatop.com)由数名来自于研发第一线的资深工程师发起成立,致力并专注于微波、射频、天线设计研发人才的培养;我们于 2006 年整合合并微波 EDA 网(www.mweda.com),现已发展成为国内最大的微波射频和天线设计人才培养基地,成功推出多套微波射频以及天线设计经典培训课程和 ADS、HFSS 等专业软件使用培训课程,广受客户好评;并先后与人民邮电出版社、电子工业出版社合作出版了多本专业图书,帮助数万名工程师提升了专业技术能力。客户遍布中兴通讯、研通高频、埃威航电、国人通信等多家国内知名公司,以及台湾工业技术研究院、永业科技、全一电子等多家台湾地区企业。

易迪拓培训推荐课程列表: <http://www.edatop.com/peixun/tuijian/>



射频工程师养成培训课程套装

该套装精选了射频专业基础培训课程、射频仿真设计培训课程和射频电路测量培训课程三个类别共 30 门视频培训课程和 3 本图书教材;旨在引领学员全面学习一个射频工程师需要熟悉、理解和掌握的专业知识和研发设计能力。通过套装的学习,能够让学员完全达到和胜任一个合格的射频工程师的要求...

课程网址: <http://www.edatop.com/peixun/rfe/110.html>

手机天线设计培训视频课程

该套课程全面讲授了当前手机天线相关设计技术,内容涵盖了早期的外置螺旋手机天线设计,最常用的几种手机内置天线类型——如 monopole 天线、PIFA 天线、Loop 天线和 FICA 天线的设计,以及当前高端智能手机中较常用的金属边框和全金属外壳手机天线的设计;通过该套课程的学习,可以帮助您快速、全面、系统地学习、了解和掌握各种类型的手机天线设计,以及天线及其匹配电路的设计和调试...

课程网址: <http://www.edatop.com/peixun/antenna/133.html>



WiFi 和蓝牙天线设计培训课程

该套课程是李明洋老师应邀给惠普 (HP)公司工程师讲授的 3 天员工内训课程录像,课程内容是李明洋老师十多年工作经验积累和总结,主要讲解了 WiFi 天线设计、HFSS 天线设计软件的使用,匹配电路设计调试、矢量网络分析仪的使用操作、WiFi 射频电路和 PCB Layout 知识,以及 EMC 问题的分析解决思路等内容。对于正在从事射频设计和天线设计领域工作的您,绝对值得拥有和学习! ...

课程网址: <http://www.edatop.com/peixun/antenna/134.html>



CST 学习培训课程套装

该培训套装由易迪拓培训联合微波 EDA 网共同推出,是最全面、系统、专业的 CST 微波工作室培训课程套装,所有课程都由经验丰富的专家授课,视频教学,可以帮助您从零开始,全面系统地学习 CST 微波工作的各项功能及其在微波射频、天线设计等领域的设计应用。且购买该套装,还可超值赠送 3 个月免费学习答疑...

课程网址: <http://www.edatop.com/peixun/cst/24.html>



HFSS 学习培训课程套装

该套课程套装包含了本站全部 HFSS 培训课程,是迄今国内最全面、最专业的 HFSS 培训教程套装,可以帮助您从零开始,全面深入学习 HFSS 的各项功能和在多个方面的工程应用。购买套装,更可超值赠送 3 个月免费学习答疑,随时解答您学习过程中遇到的棘手问题,让您的 HFSS 学习更加轻松顺畅...

课程网址: <http://www.edatop.com/peixun/hfss/11.html>

ADS 学习培训课程套装

该套装是迄今国内最全面、最权威的 ADS 培训教程,共包含 10 门 ADS 学习培训课程。课程是由具有多年 ADS 使用经验的微波射频与通信系统设计领域资深专家讲解,并多结合设计实例,由浅入深、详细而又全面地讲解了 ADS 在微波射频电路设计、通信系统设计和电磁仿真设计方面的内容。能让您在最短的时间内学会使用 ADS,迅速提升个人技术能力,把 ADS 真正应用到实际研发工作中去,成为 ADS 设计专家...

课程网址: <http://www.edatop.com/peixun/ads/13.html>



我们的课程优势:

- ※ 成立于 2004 年,10 多年丰富的行业经验,
- ※ 一直致力并专注于微波射频和天线设计工程师的培养,更了解该行业对人才的要求
- ※ 经验丰富的一线资深工程师讲授,结合实际工程案例,直观、实用、易学

联系我们:

- ※ 易迪拓培训官网: <http://www.edatop.com>
- ※ 微波 EDA 网: <http://www.mweda.com>
- ※ 官方淘宝店: <http://shop36920890.taobao.com>